

### Application

EXPERTplus records the valve condition while the process is running (in automatic mode) and generates messages on the required maintenance work. In addition, numerous tests can be performed in manual mode to pinpoint emerging faults.

EXPERTplus is a diagnostic firmware integrated into the positioner which allows the predictive, status-oriented maintenance of valves with pneumatic actuators. The diagnostic functions of EXPERTplus are completely integrated into the Type 3730-6 Positioner. Diagnostic data are compiled, saved and analyzed in the positioner itself. The data are analyzed and classified status messages are generated about the condition of the valve based on the NAMUR Recommendation NE 107 on the state of the valve.

### Special features

- Diagnostic firmware for control valves
- Start-up monitoring
- Diagnostic functions performed without any additional sensors (except for seat leakage detection using the optional leakage sensor)
- Cyclical polling of diagnosis data, multiplexer-capable
- Diagnostic data and test analysis saved in the positioner
- Logging with operating hours counter allows data and events to be sorted by time
- Automatic generation of status messages
- Status classification and condensed state based on NAMUR Recommendation NE 107
- Minimum and maximum temperature readings with details on how long the limits have been exceeded
- Classified status messages and condensed state can be read in the operator software, at the positioner display or issued at the fault alarm contact

### Operator software

The TROVIS-VIEW software, which allows the user to access, read and edit the diagnosis, is easy to learn. The integration options including eDD, eEDD, FDT/DTM allow the diagnostic functions to be also used in other engineering tools.

- **TROVIS-VIEW** · Operator interface used to configure various SAMSON devices
- **FDT** · Field device tool for the manufacturer-independent integration of field devices
- **DTM** · Device type manager to describe the device and communication properties
- **DD/eDD** · Device description/enhanced device description



**Fig. 1:** Control valve with Type 3730-6 Electropneumatic Positioner with HART® communication and pressure sensors

## Diagnostic functions

The diagnostic functions in EXPERTplus are divided into two categories: monitoring and dynamic tests.

### • Monitoring tests

Data are compiled, saved and analyzed by the positioner while the process is running without disrupting it. The positioner follows the set point to position the valve. A classified status alarm or fault alarm is generated if the positioner detects an event.

### • Dynamic tests

Similar to the monitoring tests, data are compiled, saved and analyzed by the positioner. However, in this case, the valve position is not determined by the set point, but by the active test. The dynamic tests can only be started when the conditions in the plant allow it (e.g. plant shutdown or service work in the workshop).

Table 1 shows the diagnostic functions with their test analyses.

## 1 Initialization results

EXPERTplus monitors the valve during automatic initialization to ensure trouble-free start-up. For this purpose, the positioner determines the nominal range, opening and closing times of the valve as well as the control parameters, such as proportional-action coefficient (Kp level) and the derivative-action time (Tv level). Additionally, initialization errors including supply pressure status, attachment, initialization time exceeded or pin/switch position are reported.

Main window		Diagnostic overview	
Start-up > Initialization result			
Name		Value	Unit
<b>Initialization result</b>			
Device initialized		Yes	
Detected nominal range		14.9	mm
Min. transit time OPEN		2.2	s
Min. transit time CLOSED		6.6	s
Supply pressure during initialization		4.9	bar
Detected proportional-action coefficient Kp level		7	
Detected derivative-action time Tv level		2	
Switch position (ATO/ATC)		ATO (air to open; closing)	
<b>Initialization error</b>			
Supply pressure status		All right	
x > range		No	
Δx < range		No	
Attachment		No	
Initialization time exceeded		No	
Initialization/internal solenoid valve/forced venting		No	
Transit time not reached		No	
Pin/switch position		No	
No emergency mode		No	
Valve signature canceled		No	

## 2 Diagnostics and measured process values

EXPERTplus shows the key process variables collected by the positioner, such as set point  $w$ , valve position  $x$ , operating state, supply pressure  $p_s$  and signal pressure  $p_{out}$ . Leakage in the pneumatic system is additionally shown for control valves.

Tag no.:	SAG	
Operating hours counter:	00:14:13	
Current operating mode:	Automatic	
Switch position (ATO/ATC):	ATO (air to open; closing)	
Centralized fault:		
Set point [w]:	77,3 %	
Actual value [x]:	77,3 %	
Error [e]:	0,0 %	
Supply pressure:	5,0 bar	
Signal pressure p out:	0,6 bar	
Temperature:	24,0 °C	

Performance	Valve	Actuator	Positioner
o.k.	o.k.	o.k.	o.k.

**Table 1: Overview of EXPERTplus functions**

Function	Analysis	See section
Initialization result	Nominal range, min. transit times OPEN and CLOSED, supply pressure during initialization, proportional-action coefficient (Kp level), derivative-action time (Tv level), switch position ATO/ATC (closed position) <b>Messages:</b> Supply pressure status, x > range, $\Delta x < \text{range}$ , attachment, initialization time exceeded, internal solenoid valve/forced venting/supply pressure, transit time reached, pin/switch position, no emergency mode, valve signature canceled	1
Measured process values	Condensed state, operating hours counter, set point w, valve position x, set point deviation e, operating status, supply pressure, signal pressure, absolute total valve travel, inside temperature, dynamic load factor, differential pressure, flow rate	2
<b>Monitoring</b>		
Status messages	Display and logging of classified status messages and condensed state	3.1
Condensed state		3.2
Logging		3.3
<b>Monitoring tests</b>		
Data logger	Depending on the trigger condition selected	4.1.1
Valve signature	<b>Messages:</b> Friction change, supply pressure, pneumatic leakage, actuator springs defect	4.1.2
Valve position histogram	<b>Messages:</b> Course of the manipulated variable range, manipulated variable range	4.1.3
Set point deviation histogram	Average set point deviation <b>Messages:</b> Manipulated variable range limitation, seat leakage, positioner-valve linkage	4.1.4
Cycle counter histogram	Dynamic stress factor <b>Message:</b> Packing leakage	4.1.5
Leakage sensor	<b>Message:</b> Seat leakage	4.1.6
Course of end position	Zero shift <b>Message:</b> Course of end position	4.1.7
<b>Dynamic tests</b>		
Valve dead band	Dead band	4.2.1
Binary input	–	5

## 3 Monitoring

### 3.1 Status messages

The valve diagnostics integrated into the positioner generates classified status messages based on NAMUR recommendation NE 107.

Messages generated from the analysis of the diagnosis can be classified according to the possible causes.

The following classifications are possible:

- **No message**  
If an event is classified as “No message”, this event does not have any affect on the condensed state.
- **Function check**  
Test or calibration procedures are performed in the positioner. The positioner is temporarily unable to perform its control task as long as the procedure is taking place.
- **Maintenance required/maintenance demanded**  
The positioner still performs its control task (with restrictions). A maintenance demand or above average wear has been determined. The wear tolerance will soon be exhausted or is reducing at a faster rate than expected. Maintenance is necessary in the medium term.
- **Out of specification**  
The positioner is running outside the specified operating conditions.
- **Failure**  
The positioner cannot perform its control task due to a functional fault in the positioner itself or in one of its peripherals or an initialization has not yet been successfully completed.

### 3.2 Condensed state based on NAMUR Recommendation NE 107

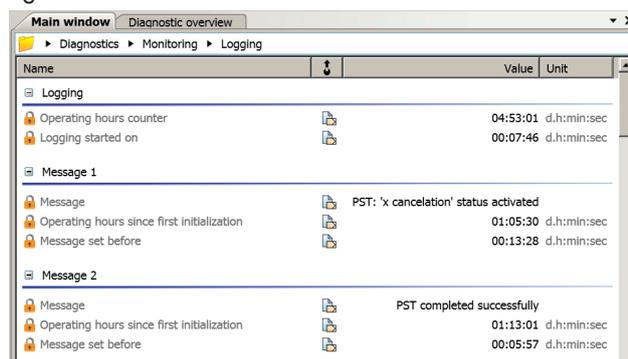
To provide a better overview on the condition of the valve, all status messages are summarized in a condensed state which is made up from a summary of all classified messages in the positioner. The status message with the highest priority determines which condensed state is set.

The condensed state is also issued at the fault alarm output.

Status message	TROVIS-VIEW or DTM	Positioner	Priority
Failure	 red		
Function check	 orange	Text e.g. <b>TESTING, TUNE</b> or <b>TEST</b>	
Out of specification	 yellow	 blinking	
Maintenance required/maintenance demanded	 blue		
No message, OK	 green		

### 3.3 Logging

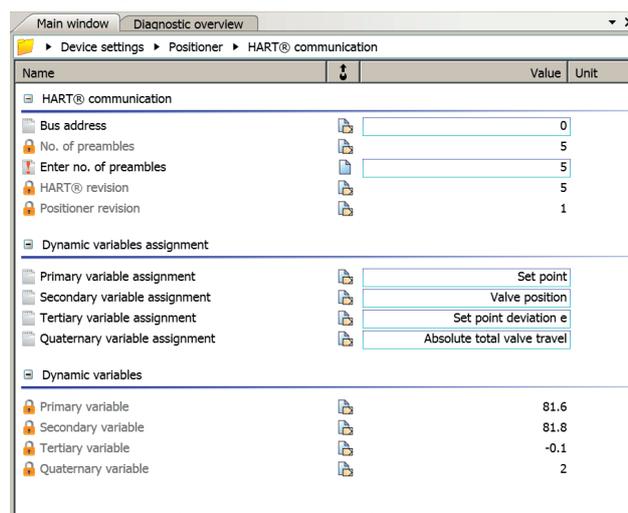
The positioner saves the last 30 plain-text messages that have been generated including time stamp and details on how long the message exists. The message logging generated by the diagnostics can be deactivated.



Name	Value	Unit
<b>Logging</b>		
Operating hours counter	04:53:01	d.h:min:sec
Logging started on	00:07:46	d.h:min:sec
<b>Message 1</b>		
Message	PST: 'x cancelation' status activated	
Operating hours since first initialization	01:05:30	d.h:min:sec
Message set before	00:13:28	d.h:min:sec
<b>Message 2</b>		
Message	PST completed successfully	
Operating hours since first initialization	01:13:01	d.h:min:sec
Message set before	00:05:57	d.h:min:sec

### 3.4 Dynamic HART® variables

The four dynamic HART® variables can be assigned to variables, such as set point, direction of action set point, set point after transit time specification, valve position, set point deviation, absolute total valve travel, binary input status, internal solenoid valve/forced venting status, condensed state, temperature, sound level (leakage sensor), ambient pressure, signal pressure, supply pressure, flow rate and differential pressure as well as all active errors.



Name	Value	Unit
<b>HART@ communication</b>		
Bus address	0	
No. of preambles	5	
Enter no. of preambles	5	
HART@ revision	5	
Positioner revision	1	
<b>Dynamic variables assignment</b>		
Primary variable assignment	Set point	
Secondary variable assignment	Valve position	
Tertiary variable assignment	Set point deviation e	
Quaternary variable assignment	Absolute total valve travel	
<b>Dynamic variables</b>		
Primary variable	81.6	
Secondary variable	81.8	
Tertiary variable	-0.1	
Quaternary variable	2	

## 4 Diagnostic functions

The analysis of diagnostic functions highlights possible valve malfunctions.

### 4.1 Monitoring tests

By permanently recording raw diagnostic data ( $w$ ,  $x$ ,  $p_{out}$  and  $e$ ) in the positioner, the user can gather information about how the valve behaves under process conditions.

Signal logging enables an analysis of the current measuring scope as well as of the positioner's entire service life.

The following statements can be made, for example:

- Valve positioning range OK
- Valve mainly operates in the upper or the lower end position
- Dynamic stress factor

As a result, recommendations for predictive maintenance can be given. In addition, immediately required action is reported.

#### 4.1.1 Data logger

The data logger records the following variables: *valve position*  $x$ , *set point*  $w$ , *set point deviation*  $e$  and *signal pressure*  $p_{out}$ .

The recorded data are plotted against time in a graph. The last 100 data points per variable are saved in a FIFO memory in the positioner. The time between recording data points is user-definable.

In addition to permanent logging, data logging can be started automatically while the process is running, provided a defined trigger condition is met.

#### 4.1.2 Valve signature

The valve signature plots the *signal pressure*  $p_{out}$  as a function of *valve position*  $x$ , the course of supply pressure (*supply pressure*  $p_s$  vs. the number of measurements) and friction (hysteresis vs. *valve position*  $x$ ).

To perform the monitoring tests while the process is running, the reference curve (*signal pressure*  $p_{out}$  vs. *valve position*  $x$ ) must be recorded first.

The valve signature allows EXPERTplus to detect the following malfunctions:

- Actuator spring compression reduced
- Zero error
- Supply pressures too high, fluctuates, too low, does not exist or the permissible limits exceeded
- Lower/higher friction change in entire range/in mid-position/near max. OPEN position/near CLOSED position

#### 4.1.3 Valve position histogram

The valve travel histogram is a statistical analysis of the plotted valve positions. It provides information about where the valve mainly works during its service life and whether it shows a recent trend concerning changes in its operating range.

A short-term histogram and a long-term histogram are plotted.

EXPERTplus generates the corresponding message when the positioner mainly works near or in the CLOSED/max. OPEN position or an operating range shift is detected.

#### 4.1.4 Set point deviation histogram

The set point deviation histogram contains a statistical analysis of any set point deviations recorded. It provides a summary of how often and to which level a set point deviation has occurred during the valve service life and whether malfunctions may arise. Ideally, the set point deviation should be as small as possible.

A short-term histogram and a long-term histogram are plotted.

EXPERTplus generates a corresponding message when the histogram pinpoints to internal valve leakage or an limitation of the upper or lower manipulated variable range.

#### 4.1.5 Cycle counter histogram

The cycle counter histogram provides a statistical analysis of the cycles. As a result, the cycle counter also provides information on the dynamic stress of a bellows seal and/or packing.

#### 4.1.6 Leakage sensor

By upgrading the positioner with a leakage sensor, it is possible to detect seat leakage when the valve is in the closed position. To achieve this, the leakage sensor measures the sound pressure level (dB) while the valve is tightly shut and compares the current sound pressure level with predefined alarm limits. To be able to use the full scope of functions, the response of the leakage sensor to standardized conditions and to the prevailing process conditions must be measured. Furthermore, the limit to activate the alarm must be entered.

The positioner generates a message if the current sound pressure level exceeds one of the limits to trigger an alarm.

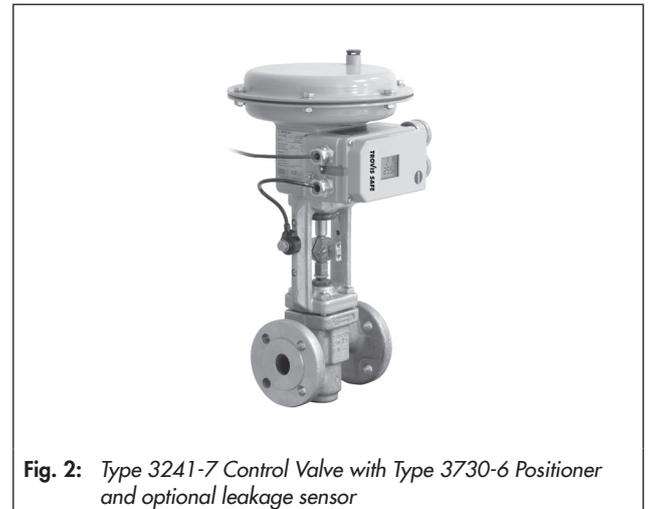


Fig. 2: Type 3241-7 Control Valve with Type 3730-6 Positioner and optional leakage sensor

### 4.1.7 Course of end position

The course of end position is used to detect an alternating zero point or a creeping zero point shift due to seat and plug wear or dirt between the seat and plug.

The course of the end position records the *valve position*  $x$  and the *signal pressure*  $p_{out}$  together with the time stamp by the operating hours counter when the valve moves to the lower end position. The new recorded valve position is compared to the last saved zero point.

A graph of the recorded valve positions at the lower end position is plotted over time.

EXPERTplus generates a corresponding message when the end position shifts.

## 4.2 Dynamic tests

For reasons of safety, the dynamic tests can only be started when the positioner is in the MAN operating mode. Therefore, it is important to make sure before starting a test whether the conditions (in the plant or process) allow the valve to move. The dynamic tests provide a trend showing the current valve state, any possible existing malfunctions and help to pinpoint faults and to schedule predictive maintenance work.

### 4.2.1 Valve dead band

The difference in *set point*  $w$  that causes a minimal change in the *valve position*  $x$  is termed 'dead band'.

The valve dead band is affected by the friction hysteresis and the elastic processes in the valve stem packing.

The positioner specifies the *set point*  $w$  in a defined test range in small steps and records the response of the *valve position*  $x$ .

The ascendent and descendent are plotted within the test range. The response of the *valve position*  $x$  to the *change in set point* ( $\Delta w$ ) is plotted in a graph.

The dead band is analyzed in the positioner when a step height is smaller than 0.2 %.

## 5 Binary input

The optional binary input allows various actions to be performed which also affect the diagnostic functions. If an action is started over the binary input, this action is logged.

## Visualization and parameterization

The TROVIS-VIEW software or the DTM tool generate graphs from the data, test results and status messages collected by the diagnostic firmware in the positioner.

In addition, the diagnostic data can also be made accessible to other engineering tools using the DD (device description) or EDD (enhanced device description), which enables the data to be displayed in a graph, e.g. using Siemens PDM, AMS. How the data are displayed depends on the tool.

### Graphs in TROVIS-VIEW 4, DTM, EDD

The Trend Viewer function in TROVIS-VIEW allows the following compiled raw data and test results as well as variables ( $w$ ,  $x$ ,  $e$ ,  $p_{out}$ ) recorded in the data logger to be displayed in a graph:

- Process variables
- Valve signature
- Course of end position
- Valve dead band

The long-term and short-term monitoring tests described in sections 4.1.3 to 4.1.5 are displayed in bar graphs.

The valve signature and the histograms use long-term and short-term monitoring tests.

These graphs make any changes in positioning or control performance apparent to the user and support predictive maintenance.



Specifications subject to change without notice



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